

# Navigation, communication & Power Board

An OEM navigation solution for land & marine applications



### NAVIGATION BOARD

#### **Performance**

The Navigation Communication & Power board (NCPB) is designed to suit all navigation needs whether in air, land or at sea. It includes on board mounted GNSS, INS & a computer in a compact size. It easily enables the navigation for your OEM. The NCPB provides highly accurate navigation solutions for your vehicle (typical applications: bathymetry applications, environment monitoring...).

This NCPB is composed of the state-of-the-art technologies:

- Embedded computer,
- GNSS Receiver,
- Inertial Navigation System (INS)
- Power supply & communication hub for user devices (Ethernet, Serial, GPIO...).







## OEM NAVIGATION SOLUTION

#### **Adaptability**

This NCPB is design to make your integration easier. The field applications are varied. Its compact design makes it suitable for any confined space (e.g. AUV, USV...). It is designed for low-power requirements for long duration uses at remotely accessible areas.





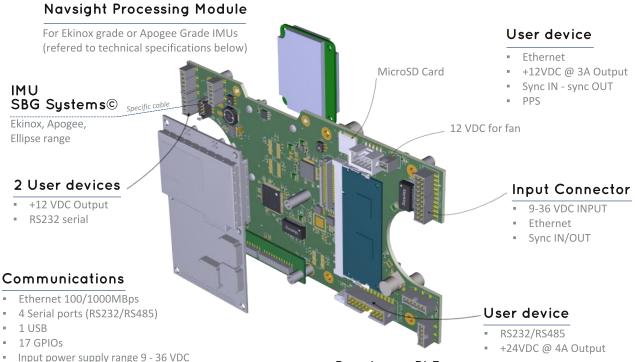








## NCPB CONFIGURATION



#### **GNSS OEM Receiver**

Supported models indicated in technical specifications below

#### Raspberry Pi 3+

- On board communication management
- Linux OS
- Storage for data acquisition
- Configurable for full autonomy
- Accessible GPIOs

# TECHNICAL SPECIFICATIONS

#### Configuration options & Technical specifications

GNSS:

- Hemisphere H328 or Vega<sup>™</sup> 40 GNSS Compass board.
- Trimble BD992 Dual Antenna, positioning & heading with RTK omniSTAR support.
- Trimble BD992-INS.

INS/IMU: • Ellipse Series

Navsight Ekinox Series

Computer: • Raspberry Pi CM3+

Power supplies:

- Communications:
- Input power range: +12 to 36 VDC
- Power requirement:
- Power outputs:

GPS, GLN, GAL, QZSS, BDS, L-Band (Atlas), IRNSS (Vega<sup>™</sup> 40 only) heading (0.04°@ 2m baseline), L1/L2, RTK 1cm, rover, 20 Hz (option), 0.5° pitch & roll (Vega<sup>™</sup> 40) / 1° pitch & roll (H328).

GPS, GLN, GAL, BDS, L-Band (Omnistar), heading (0.09° @ 2m baseline), L1/L2/L5/E6, RTK 1cm, rover, 50 Hz.

GPS, GLN, GAL, BDS, L-Band (Omnistar), heading (0.09° @ 2m baseline), L1/L2/L5/E6, RTK 1cm, rover, 100 Hz, 0.1° pitch & roll.

 $0.1^{\circ}$  pitch & roll,  $1^{\circ}$  heading (magnetometer), 5 cm real-time heave.

0.02° pitch & roll, 0.05° heading (w/ GNSS), 5 cm real-time heave.

32 Gb eMMC, 1Gb SDRAM (+32Gb SD card), Cortex A53 (ARM) 64-bits.

Ethernet 100BASE-T and 1000BASE-T.

Operating temperature 0° to 70°C 20 W INS + GNSS solutions.

+12 VDC @ 3A (All outputs combined) +24 VDC @ 4A (Isolated power supply).

## FROM A TO Z



Systems design engineering.



Software development for our own products or for new interfaces with customers systems.



Remote technical support.

# A WIDE RANGE OF APPLICATIONS



Marine services



Research



Environment



**Natural Ressources** 



Archeology



Military REA

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